Patient Name

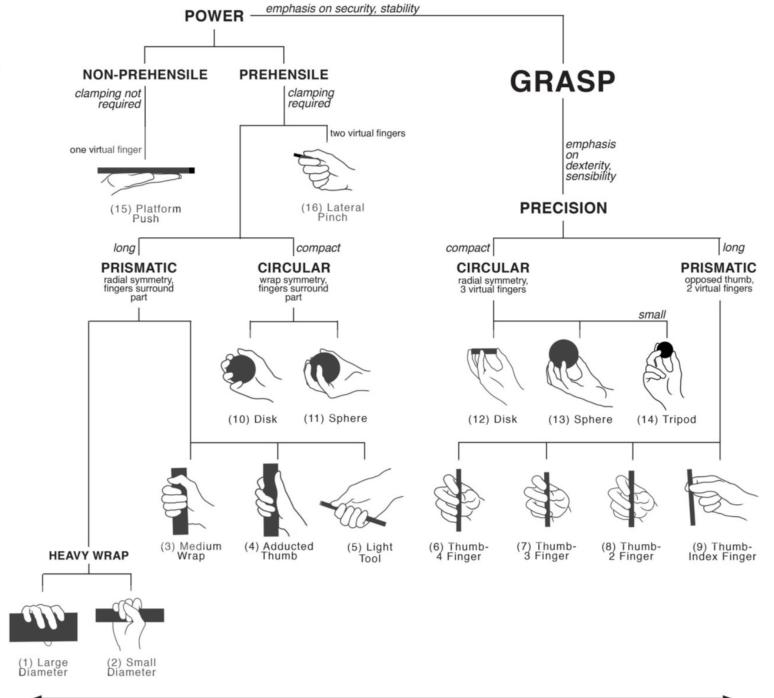
Hand Function Chart with and without prosthesis

Patient can perform without prosthesis

gross task and geometry

detailed task and geometry

Additional grasps <u>patient can perform</u> with Naked Prosthetics prosthesis



P R O S T H E T I C S

Cutkosky MR. On Grasp Choice, Grasp Models, and the Design of Hands for Manufacturing Tasks. *IEEE Transactions on Robotics and Automation 1989;5(3):269-79.*